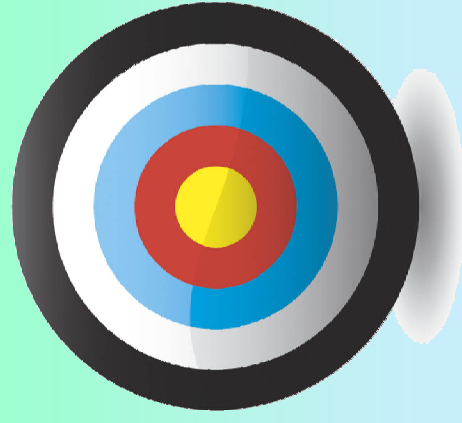
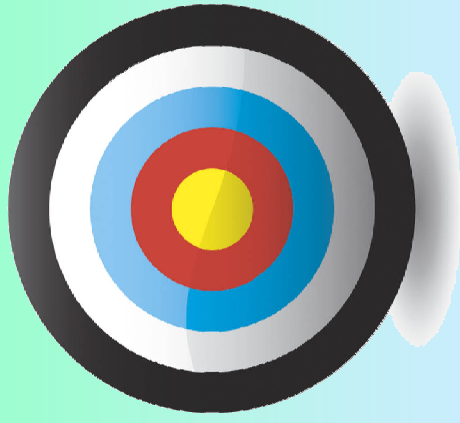


*I am learning to predict where
the programmable robot will
be after I make it move.

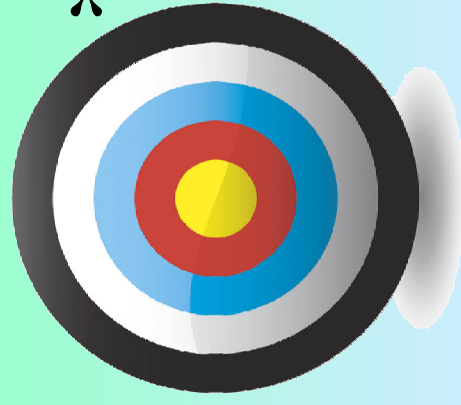


*I can predict where the
programmable robot will
be after I make it move.



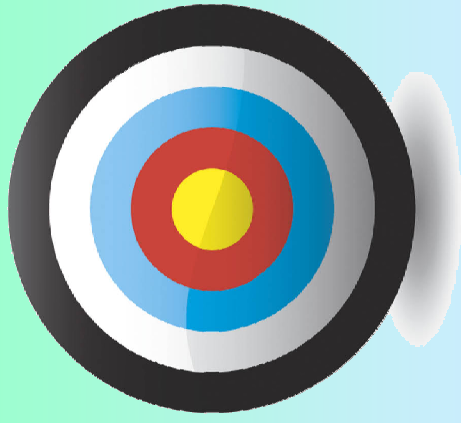


*I am learning to give instructions that will make the programmable robot move.

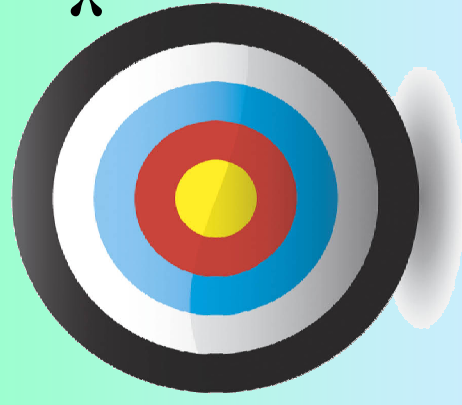


*I can give instructions that can make the programmable robot move.



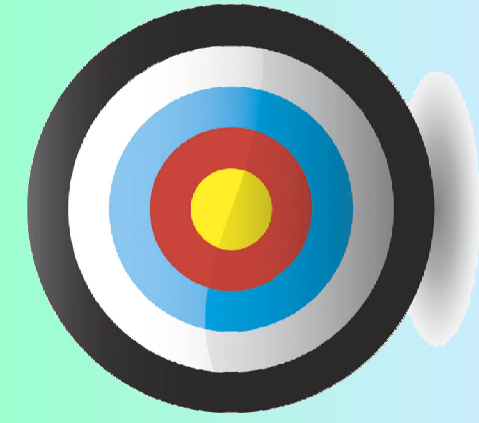


* I am learning to change my instructions so that the programmable robot will move to a different place.

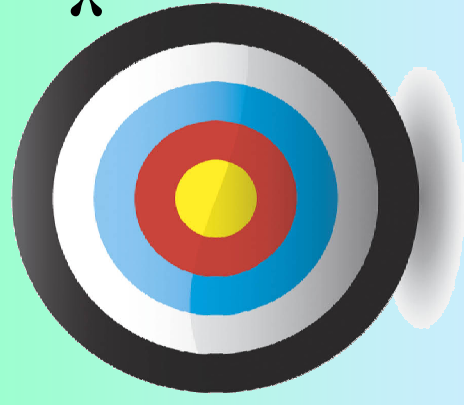


* I can change my instructions so that the programmable robot will move to a different place.



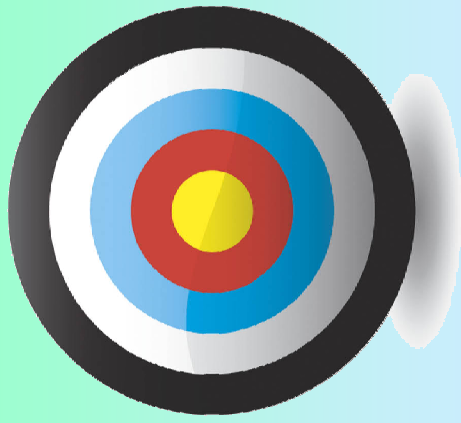


*I am learning to make the
programmable robot turn
in different ways.

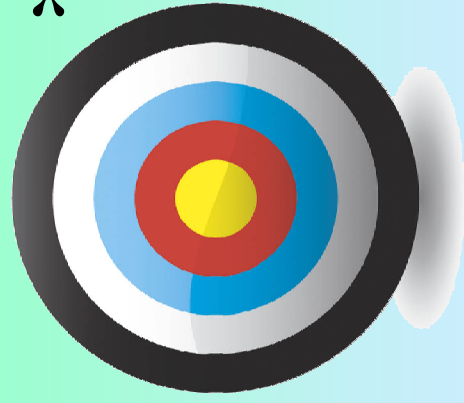


*I can make the
programmable robot turn in
different ways.



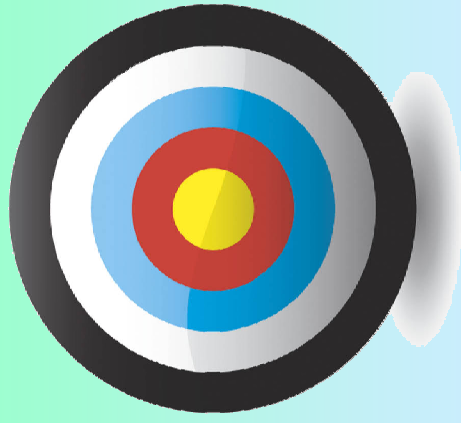


*I know how to
make predictions.

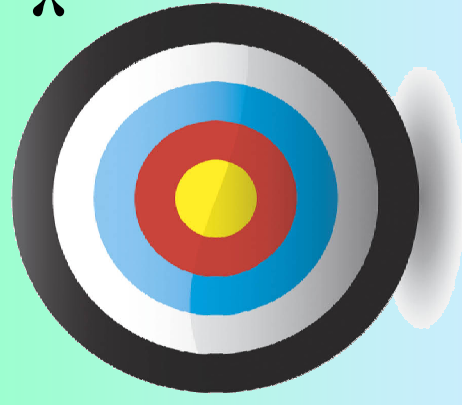


*I can write instructions
using 90° and 180°
angles.





*I know how to
combine instructions.



*I know how to make
predictions using
patterns.

